# ON A FOURIER PROBLEM FOR EVOLUTION DIFFERENTIAL-FUNCTIONAL EQUATIONS WITH NONLOCAL BOUNDARY CONDITIONS

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#### INTRODUCTION.

The boundary value problems with nonlocal boundary conditions have been treated in many works. Individually, Day [1] while studying quasistatic thermoelasticity posed a model involving parabolic equation with nonlocal boundary condition. This model has been expanded into more general problems [1,2]. The results of these papers concern the boundary value problems with an initial condition.

In the current paper, we consider Fourier Problem (the problem without initial conditions) for evolution differential-functional equations with nonlocal boundary conditions. Note that Fourier Problem for strongly non-linear parabolic equations of the second order with nonlocal boundary conditions of the type of periodicity was investigated in [5].

Let us introduce several concepts and symbols we need later. Let D be a domain in the space  $\mathbb{R}^{n+1}_{x,t}$ . Denote by  $C^{\alpha,\alpha/2}(\overline{D})$ , where  $\alpha$  is a number from interval [0;1], Banach space of real-valued functions, which are continuous in  $\overline{D}$ , if  $\alpha=0$ , and Hölder continuous functions in  $\overline{D}$  with exponent  $\alpha$ , if  $\alpha>0$  (see definitions in [8], p.16). Denote by  $C^{2+\alpha,1+\alpha/2}(\overline{D})$  a subspace of space  $C^{\alpha,\alpha/2}(\overline{D})$  which consists of functions w such that  $\{w_{x_ix_j}\ (\{i,j\}\subset\{1,...,n\}), w_t\}\subset C^{\alpha,\alpha/2}(\overline{D})$ . The norms in these spaces are denoted by  $||\cdot||_{\alpha,\alpha/2}^D$  and  $||\cdot||_{2+\alpha,1+\alpha/2}^D$ , respectively. If D is unbounded domain then denote by  $C^{\alpha,\alpha/2}_{loc}(\overline{D})$ ,  $C^{2+\alpha,1+\alpha/2}_{loc}(\overline{D})$  the spaces of functions defined in  $\overline{D}$  which restrictions on the closure of any bounded subdomain D' of domain D belong to  $C^{\alpha,\alpha/2}(\overline{D'})$  and  $C^{2+\alpha,1+\alpha/2}(\overline{D'})$ , respectively  $(\alpha\in[0;1])$ . Set  $C(\overline{D})\stackrel{def}{=} C^{0,0}_{loc}(\overline{D})$ ,  $C_{loc}(\overline{D})\stackrel{def}{=} C^{0,0}_{loc}(\overline{D})$ . In the case when Q is conjugation of domain D and the part of its boundary, we denote by  $C^{\alpha,\alpha/2}_{loc}(Q)$ ,  $C^{2+\alpha,1+\alpha/2}_{loc}(Q)$  the spaces of functions which restrictions on closure of arbitrary bounded subdomain D' of domain D such that  $\overline{D'} \subset Q$ , belong to spaces  $C^{\alpha,\alpha/2}(\overline{D'})$  and  $C^{2+\alpha,1+\alpha/2}(\overline{D'})$ , respectively  $(\alpha\in[0;1])$ .

1. STATEMENT OF THE PROBLEM AND FORMULATION OF MAIN RESULTS.

Let  $Q = \Omega \times (-\infty, T]$ ,  $0 < T < +\infty$ ,  $\Omega$  be a bounded domain in  $\mathbb{R}^n_x$  with smooth boundary  $\partial \Omega$ ,  $\Sigma = \partial \Omega \times (-\infty, T]$ .

We consider a problem

$$Pu(x,t) \equiv rac{\partial u(x,t)}{\partial t} - Lu(x,t) + a(x,t)u(x,t) -$$

$$-f(x, t, u(x, t); u(\cdot, t)) = \hat{f}(x, t), \quad (x, t) \in Q,$$
(1)

$$Bu(x,t) \equiv u(x,t) - g(x,t,u(x,t);u(\cdot,t)) = h(x,t), \quad (x,t) \in \Sigma,$$
 (2)

where

$$Lu(x,t) \equiv \sum_{i,j=1}^{n} a_{ij}(x,t) \frac{\partial^{2} u(x,t)}{\partial x_{i} \partial x_{j}} + \sum_{i=1}^{n} a_{i}(x,t) \frac{\partial u(x,t)}{\partial x_{i}};$$

 $f(x,t,\xi;\cdot):C(\overline{\Omega})\to\mathbb{R}\;,\;(x,t,\xi)\in Q\times\mathbb{R}\;,\;\mathrm{and}\;\;g(x,t,\eta;\cdot):C(\overline{\Omega})\to\mathbb{R}\;,\;(x,t,\eta)\in\Sigma\times\mathbb{R},\;$  are families of functionals.

Henceforth this problem is called Problem (1),(2).

We impose the following main conditions on the data-in:

- (A1) functions  $a_{ij}, a_i, a$  are continuous in  $Q, \{i, j\} \subset \{1, ..., n\}$ ;
- (A2)  $a_{ij} = a_{ji}, \{i, j\} \subset \{1, ..., n\}$ , and for arbitrary point  $(x, t) \in Q$  and for all  $\xi = (\xi_1, ..., \xi_n) \in \mathbb{R}^n$  the following inequality holds

$$\sum_{i,j=1}^{n} a_{ij}(x,t)\xi_{i}\xi_{j} \geqslant \mu(t) \sum_{s=1}^{n} \xi_{s}^{2},$$

where  $\mu(t) \geqslant 0$ ,  $t \in (-\infty, T]$ ;

(A3) for all  $v \in C(\overline{\Omega})$  functions  $f(x,t,\xi;v(\cdot))$ ,  $(x,t,\xi) \in Q \times \mathbb{R}$ ,  $g(x,t,\xi;v(\cdot))$ ,  $(x,t,\xi) \in \Sigma \times \mathbb{R}$ , are continuous, nondecreasing in  $\xi$ , i.e. for arbitrary  $\{\xi^1,\xi^2\} \subset \mathbb{R}$ , such that  $\xi^1 \geqslant \xi^2$ , the following inequalities hold:

$$f(x,t,\xi^1;v(\cdot))-f(x,t,\xi^2;v(\cdot))\geqslant 0, \qquad (x,t)\in Q,$$

$$g(x, t, \xi^1; v(\cdot)) - g(x, t, \xi^2; v(\cdot)) \geqslant 0, \qquad (x, t) \in \Sigma;$$

moreover, these functions are Lipschitz in  $\xi$ , more precisely, there exist functions  $L^f(x,t),\ (x,t)\in Q$ , and  $L^g(x,t),\ (x,t)\in \Sigma$ , such that for arbitrary  $\{\xi^1,\xi^2\}\subset \mathbb{R}$  and  $v\in C(\overline{\Omega})$ 

$$|f(x,t,\xi^{1};v(\cdot)) - f(x,t,\xi^{2};v(\cdot))| \leq L^{f}(x,t)|\xi^{1} - \xi^{2}|, \quad (x,t) \in Q,$$

$$|g(x,t,\xi^{1};v(\cdot)) - g(x,t,\xi^{2};v(\cdot))| \leq L^{g}(x,t)|\xi^{1} - \xi^{2}|, \quad (x,t) \in \Sigma;$$

(A4) functionals  $f(x,t,\xi;\cdot):C(\overline{\Omega})\to\mathbb{R}$ ,  $(x,t,\xi)\in Q\times\mathbb{R}$ , and  $g(x,t,\xi;\cdot):C(\overline{\Omega})\to\mathbb{R}$ ,  $(x,t,\xi)\in\Sigma\times\mathbb{R}$ , are G  $\hat{a}$  teaux differentiable, more precisely, for arbitrary  $v\in C(\overline{\Omega})$  there exist linear and continuous functionals  $f'_c(x,t,\xi;v(\cdot),\cdot):C(\overline{\Omega})\to\mathbb{R}$ ,  $(x,t,\xi)\in Q\times\mathbb{R}$ , and  $g'_c(x,t,\xi;v(\cdot),\cdot):C(\overline{\Omega})\to\mathbb{R}$ ,  $(x,t,\xi)\in\Sigma\times\mathbb{R}$ , such that

$$\frac{d}{ds}f(x,t,\xi;v(\cdot)+sh(\cdot))\big|_{s=0}=f_c'(x,t,\xi;v(\cdot),h(\cdot)),\quad (x,t,\xi)\in Q\times\mathbb{R},$$

$$\frac{d}{ds}g(x,t,\xi;v(\cdot)+sh(\cdot))\big|_{s=0}=g_c'(x,t,\xi;v(\cdot),h(\cdot)),\quad (x,t,\xi)\in\Sigma\times\mathbb{R},$$

for all  $h \in C(\overline{\Omega})$ ; the following inequalities hold:

$$f'_c(x,t,\xi;v(\cdot),h(\cdot))\geqslant 0,\quad g'_c(x,t,\xi;v(\cdot),h(\cdot))\geqslant 0,\quad \text{if}\quad h\geqslant 0;$$

moreover, assume that

$$||f_c'(x,t,\xi;v(\cdot),h(\cdot))||\leqslant K^f(x,t)||h||_{C(\overline{\Omega})},\quad (x,t,\xi)\in Q\times\mathbb{R},\quad v\in C(\overline{\Omega}),$$

$$||g_c'(x,t,\xi;v(\cdot),h(\cdot))||\leqslant K^g(x,t)||h||_{C(\overline{\Omega})},\quad (x,\widetilde{t},\xi)\in \Sigma\times \mathbb{R},\quad v\in C(\overline{\Omega}),$$

where  $K^f(x,t)$ ,  $(x,t) \in Q$ ,  $K^g(x,t)$ ,  $(x,t) \in \Sigma$ , are some functions;

(A5) 
$$\inf_{x \in \Omega} \left( a(x,t) - F(x,t) \right) \geqslant a_0(t), \qquad t \in (-\infty, T],$$

where  $F(x,t) \stackrel{\text{def}}{=} K^f(x,t) + L^f(x,t)$ ,  $(x,t) \in Q$ , and  $a_0$  is continuous in  $(-\infty,T]$  function;

(A6)  $G(x,t) < 1, \quad (x,t) \in \Sigma,$ 

where  $G(x,t) \stackrel{\text{def}}{=} K^g(x,t) + L^g(x,t), \quad (x,t) \in \Sigma;$ 

(A7)  $\hat{f} \in C_{loc}(Q), h \in C_{loc}(\Sigma).$ 

For the convenience of formulating and proving the results, without loss of generality let us make additional assumption

(A0) 
$$f(x,t,0,0) = 0$$
,  $(x,t) \in Q$ ,  $g(x,t,0,0) = 0$ ,  $(x,t) \in \Sigma$ .

In the sequel we assume that conditions (A0)-(A7) hold.

DEFFINITION 1. A function  $u \in C^{2,1}_{loc}(Q) \cap C_{loc}(\overline{Q})$  is called a solution of Problem (1),(2) if it satisfies equation (1) and boundary condition (2).

Before formulating of main results of the work we introduce some notations and concepts.

Let b be an arbitrary continuous in  $(-\infty, T]$  function. We denote by V(b) a set of continuous differentiable in  $(-\infty, T]$  functions  $\nu$  which satisfy

$$u'(t) < b(t), \quad t \in (-\infty, T], \qquad \int\limits_{-\infty}^T \left( b(t) - \nu'(t) \right) dt = +\infty.$$

Let us note that when  $b(t) = b_0$ ,  $t \in (-\infty, T]$ , where  $b_0 = \text{const}$ , then the set of functions  $\{ct, t \in (-\infty, T] : c \in \mathbb{R}, c < b_0\}$  is subset of V(b).

Let H be one of the sets  $Q, \overline{Q}$  or  $\Sigma$ , and  $\nu \in V(a_0)$ . Denote by  $E_{\nu}(H)$  a set of continuous functions  $q(x,t), (x,t) \in H$ , which satisfy an inequality

$$|q(x,t)| \leqslant Ke^{-\nu(t)}, \quad (x,t) \in H,$$

where  $K \geqslant 0$  is a constant which may depend on q.

We denote by  $\Phi_{x,t;\mathrm{loc}}^{\alpha,\alpha/2}$ , where  $\alpha \in (0;1]$ , a space of families of functionals  $f(x,t,\xi;\cdot)$ :  $C(\overline{\Omega}) \to \mathbb{R}$ ,  $(x,t,\xi) \in Q \times \mathbb{R}$ , such that for arbitrary numbers  $t_0 < T$ ,  $l_1 > 0$ ,  $l_2 > 0$  there exists a constant  $K \geqslant 0$  which satisfies an inequality

$$|f(x^1,t^1,\xi;v(\cdot)) - f(x^2,t^2,\xi;v(\cdot))| \leqslant K \big[ |x^1 - x^2|^{\alpha} + |t^1 - t^2|^{\alpha/2} \big]$$

 $\text{for arbitrary } \{(x^1,t^1),\ (x^2,t^2)\} \subset \Omega \times (t_0,T]\,, \text{ and any }\ \xi \in [-l_1,l_1] \ \text{ and } \ v \in C(\overline{\Omega}), \\ ||v||_{C(\overline{\Omega})} \leqslant l_2\,.$ 

THEOREM 1 (AN APRIORI ESTIMATE OF THE SOLUTION). Let  $\hat{f}/(a_0 - \nu') \in E_{\nu}(Q)$  and  $h/(1-G) \in E_{\nu}(\Sigma)$  for some  $\nu$  from  $V(a_0)$ . Then the solution of Problem (1),(2) u from  $E_{\nu}(\overline{Q})$  satisfies the following estimate:

$$|u(x,t)| \leqslant \max \Big\{ \sup_{(y,\tau) \in \Sigma} \frac{|h(y,\tau)| e^{\nu(\tau)}}{1 - G(y,\tau)}, \sup_{(y,\tau) \in Q} \frac{|\hat{f}(y,\tau)| e^{\nu(\tau)}}{a_0(\tau) - \nu'(\tau)} \Big\} \cdot e^{-\nu(t)} \equiv M_0 e^{-\nu(t)}$$
(3)

for all  $(x,t) \in \overline{Q}$ .

THEOREM 2 (UNIQUENESS OF THE SOLUTION). The solution of Problem (1),(2) from class  $E_{\nu}(\overline{Q})$ , where  $\nu \in V(a_0)$ , is unique.

For all  $k \in \mathbb{N}$  let us denote by  $Q^k = Q \cap \{(x,t) : t > -k\}, \ \Sigma^k = \Sigma \cap \{(x,t) : t > -k\}$  and define a function  $u_k \in C^{2,1}_{loc}(Q^k) \cap C(\overline{Q^k})$ , as the solution of Problem:

$$P_k u_k(x,t) = \hat{f}_k(x,t), \qquad (x,t) \in Q^k, \tag{1_k}$$

$$B_k u_k(x,t) = h_k(x,t), \qquad (x,t) \in \Sigma^k, \tag{2k}$$

$$u_k(x, -k) = 0, \qquad x \in \overline{\Omega}.$$
 (3<sub>k</sub>)

Here

$$P_k w(x,t) \equiv rac{\partial w(x,t)}{\partial t} - L w(x,t) + a(x,t) w(x,t) - f_k(x,t,w(x,t);w(\cdot,t))$$

and  $B_k w(x,t) \equiv w(x,t) - g_k(x,t,w(x,t);w(\cdot,t)) \quad \forall w \in C^{2,1}(\overline{Q}), \quad f_k(x,t,\xi;\cdot) = \zeta(t+k)f(x,t,\xi;\cdot), \quad (x,t,\xi) \in Q \times \mathbb{R}, \quad g_k(x,t,\xi;\cdot) = \zeta(t+k)g(x,t,\xi;\cdot), \quad (x,t,\xi) \in \Sigma \times \mathbb{R}, \quad h_k(x,t) = \zeta(t+k)h(x,t), \quad (x,t) \in \Sigma, \quad \hat{f}_k(x,t) = \hat{f}(x,t)\zeta(t+k), \quad (x,t) \in \overline{Q}, \quad \text{where } \zeta \text{ is smooth and monotonic in } \mathbb{R} \text{ function such that } \zeta(t) = 0 \text{ if } t \leqslant 1/2, \quad \zeta(t) = 1 \text{ if } t \geqslant 1, \quad k \in \mathbb{N}.$ 

THEOREM 3 (EXISTENCE OF THE SOLUTION). Let the following conditions hold for some  $\alpha \in (0,1]$  and  $\nu \in V(a_0)$ :

(B1) 
$$\{a_{ij}, a_i, a\} \subset C_{loc}^{\alpha, \alpha/2}(\overline{Q}), \ \partial a_{ij}/\partial x_s \in C_{loc}(\overline{Q}), \ \{i, j, s\} \subset \{1, ..., n\}; \ \mu(t) > 0, \ t \in (-\infty, T];$$

(B2) 
$$f \in \Phi_{x,t;\mathrm{loc}}^{\alpha,\alpha/2}$$
;

$$(B3) \ \hat{f} \in C^{\alpha,\alpha/2}_{\mathrm{loc}}(\overline{Q}), \ \hat{f}/(a_0-\nu') \in E_{\nu}(\overline{Q}); \ \ h \in C^{2+\alpha,1+\alpha/2}_{\mathrm{loc}}(\overline{Q}), \ h/(1-G) \in E_{\nu}(\Sigma);$$

(B4) for all 
$$k \in \mathbb{N}$$
 Problem  $(1_k) - (3_k)$  has a solution  $u_k \in C^{2+\alpha,1+\alpha/2}(\overline{Q^k})$ .

Then Problem (1),(2) has a solution u in  $E_{\nu}(\overline{Q}) \cap C_{\mathrm{loc}}^{\alpha,\alpha/2}(\overline{Q}) \cap C_{\mathrm{loc}}^{2+\alpha,1+\alpha/2}(Q)$ .

COROLLARY. Let conditions (B1)-(B3) of theorem 3 hold, moreover, the following conditions are true: (C1) there exist a family of functionals  $g^*(x,t,\xi;\cdot):C(\overline{\Omega})\to\mathbb{R}$ ,  $(x,t,\xi;\cdot)\in\overline{Q}\times\mathbb{R}$ , and a function  $\eta\in C_0^\infty(\Omega)$ ,  $0\leqslant\eta\leqslant 1$ , such that  $g(x,t,\xi;\cdot)=g^*(x,t,\xi;\cdot)$ ,  $(x,t,\xi)\in\Sigma\times\mathbb{R}$ , and for arbitrary  $(x,t)\in\overline{Q}$  and  $v\in C(\overline{\Omega})$   $g^*(x,t,0;(\eta v)(\cdot))=g^*(x,t,v(x);v(\cdot))$ , moreover,  $\tilde{g}(x,t)\stackrel{\mathrm{def}}{=} g^*(x,t,0;(\eta w)(\cdot,t))\in C^{2+\alpha,1+\alpha/2}(\overline{Q})$  for any  $w\in C_{\mathrm{loc}}^{2+\alpha,1+\alpha/2}(\overline{Q})$ ;

(C2)  $\partial \Omega \in C^{2+\alpha}$ .

Then the statement of Theorem 3 is true.

Remark 1. The functionals  $g(x,t,\xi;\cdot):C(\overline{\Omega})\to\mathbb{R},\ (x,t,\xi)\in\Sigma\times\mathbb{R}$ , from Bitsadze-Samarskii boundary condition

$$g(x,t,\xi;v(\cdot)) = \sum_{k=1}^K g_k(x,t)v(\xi_k(x)), \quad (x,t,\xi) \in \Sigma \times \mathbb{R}, \ \ v \in C(\overline{\Omega}),$$

satisfy the condition (C1) of corollary if  $K \in \mathbb{N}$ ,  $g_k \in C^{2+\alpha,1+\alpha/2}(\overline{Q})$ ,  $g_k(x,t) \geq 0$ ,  $(x,t) \in \Sigma$ ,  $k \in \{1,...,K\}$ , and functions  $\xi_k$ ,  $k \in \{1,...,K\}$ , are defined in  $\overline{\Omega}$  with values in  $\overline{\Omega_\delta} = \{x \in \Omega : dist(x,\partial\Omega) \geq \delta\}$ ,  $\delta > 0$ ,  $\xi_k \in C^{2+\alpha}(\Omega)$ .

Let  $\Pi_{\nu}$  be a space of ordered pairs of functons  $(\hat{f},h)$  such that  $\hat{f} \in C^{\alpha,\alpha/2}_{loc}(\overline{Q})$ ,  $\hat{f}/(a_0-\nu') \in E_{\nu}(\overline{Q})$ ,  $h \in C^{2+\alpha,1+\alpha/2}_{loc}(\overline{Q})$ ,  $h/(1-G) \in E_{\nu}(\Sigma)$  for  $\nu \in V(a_0)$ . Let us assume that conditions (B1),(B2),(B4) are fulfilled. Then there exists unique solution of Problem (1),(2) in  $E_{\nu}(\overline{Q})$  for arbitrary  $(\hat{f},h) \in \Pi_{\nu}$ , where  $\nu \in V(a_0)$ . In short, we write this as  $u = NZ_{\nu}(\hat{f},h)$ .

Theorem 4 (Continuous dependence on data-in). Let conditions (B1),(B2),(B4) of Theorem 3 hold. Then for arbitrary  $\varepsilon > 0$  there exists  $\delta > 0$  such that for any  $(\hat{f}_1, h_1), (\hat{f}_2, h_2) \in \Pi_{\nu}$ , satisfying conditions:

$$\sup_{(x,t)\in Q}\frac{|\hat{f}_1(x,t)-\hat{f}_2(x,t)|e^{\nu(t)}}{a_0(t)-\nu'(t)}<\delta \quad \ \ and \quad \sup_{(x,t)\in \Sigma}\frac{|h_1(x,t)-h_2(x,t)|e^{\nu(t)}}{1-G(x,t)}<\delta$$

the following inequality holds:

$$\sup_{(x,t)\in Q}|u_1(x,t)-u_2(x,t)|e^{\nu(t)}<\varepsilon,$$

where  $u_i = NZ_{\nu}(\hat{f}_i, h_i), \quad i \in \{1, 2\}.$ 

## 2. AUXILIARY STATEMENTS

Let  $t_0$  be an arbitrary fixed number in  $(-\infty, T)$ . Set  $Q_0 = \Omega \times (t_0, T]$  and  $\Sigma_0 = \partial \Omega \times (t_0, T]$  where  $0 < T < +\infty$ .

LEMMA 1. Let functions  $\tilde{u}, \hat{u} \in C^{2,1}(Q_0) \cap C(\overline{Q_0})$  fulfil the inequalities

$$P\tilde{u}(x,t) < P\hat{u}(x,t), \quad (x,t) \in Q_0,$$

$$B\tilde{u}(x,t) < B\hat{u}(x,t), \quad (x,t) \in \Sigma_0, \qquad \tilde{u}(x,t_0) < \hat{u}(x,t_0), \quad x \in \overline{\Omega}. \tag{4}$$
Then  $\tilde{u}(x,t) < \hat{u}(x,t)$  for all  $(x,t) \in \overline{Q_0}$ .

*Proof.* Let us assume a contradiction. Let  $t^* \in (t_0, T]$  be a maximum value of variable t such that  $\tilde{u}(x,t) < \hat{u}(x,t)$  for all  $(x,t) \in \overline{Q_0} \cap \{(x,t) : t_0 \leq t < t^*\}$ . Then there exists a point  $x^* \in \overline{\Omega}$  such that  $\tilde{u}(x^*,t^*) = \hat{u}(x^*,t^*)$ .

It follows from the third inequality of (4) that  $t^* > t_0$ . Using (5) we next show that  $(x^*, t^*) \notin \Sigma_0$ . Assuming that  $(x^*, t^*) \in \Sigma_0$  then for the function  $w \stackrel{\text{def}}{=} \tilde{u} - \hat{u}$  by the second inequality of (4) and condition (A4) we have

$$\begin{split} 0 &= w(x^*,t^*) = g(x^*,t^*,\tilde{u}(x^*,t^*);\tilde{u}(\cdot,t^*)) - g(x^*,t^*,\hat{u}(x^*,t^*);\hat{u}(\cdot,t^*)) + \\ &\quad + B\tilde{u}(x^*,t^*) - B\hat{u}(x^*,t^*) < 0, \end{split}$$

but this contadicts the statement of lemma.

It leads to the fact that the function w in  $\overline{Q_0} \cap \{(x,t): t_0 \leq t \leq t^*\}$  takes a maximum value at the point  $(x^*,t^*) \in Q_0$  and it equals zero. Thus, using condition (A2) we have

$$\frac{\partial w(x^*,t^*)}{\partial t} \geqslant 0, \ \frac{\partial w(x^*,t^*)}{\partial x_s} = 0, \ \sum_{i,j=1}^n a_{ij}(x^*,t^*) \frac{\partial^2 w(x^*,t^*)}{\partial x_i \partial x_j} \leqslant 0.$$

Hence and by condition (A4) it follows

$$P\tilde{u}(x^*,t^*) - P\hat{u}(x^*,t^*) \geqslant 0,$$

but this contradicts the third inequality of (4).  $\square$ 

LEMMA 2. Assume that all conditions of Lemma 1 are fulfilled and the inequalities (4) are nonstrict. Then  $\tilde{u}(x,t) \leqslant \hat{u}(x,t)$  for all  $(x,t) \in \overline{Q_0}$ .

*Proof.* Let us consider an auxiliary function  $\hat{u}_{\lambda}(x,t) = \hat{u}(x,t) + \lambda e^{m^*t}, (x,t) \in \overline{Q_0}$ , where  $\lambda > 0$ ,  $m^* + a_0(t) > 0$ ,  $t \in [0,T]$ . Using conditions (A3)-(A5) we obtain

$$P\hat{u}_{\lambda}(x,t) = P\hat{u}(x,t) + \lambda e^{m^*t}(m^* + a(x,t)) - [f(x,t,\hat{u}(x,t) + \lambda e^{m^*t};\hat{u}(\cdot,t) + \lambda e^{m^*t}) - f(x,t,\hat{u}(x,t);\hat{u}(\cdot,t))] > P\hat{u}(x,t), (x,t) \in Q_0.$$

Since  $P\tilde{u}(x,t) \leqslant P\hat{u}(x,t)$ , and  $P\hat{u}(x,t) < P\hat{u}_{\lambda}(x,t)$ , then  $P\tilde{u}(x,t) < P\hat{u}_{\lambda}(x,t)$ ,  $(x,t) \in Q_0$ . It follows from conditions (A3), (A4) and (A6) that

$$B\hat{u}_{\lambda}(x,t)\geqslant B\hat{u}(x,t)+\lambda e^{m^*t}(1-G(x,t))>B\hat{u}(x,t),\quad (x,t)\in\Sigma_0.$$

Hence, using the fact that  $\tilde{u}(x,t_0) < \hat{u}_{\lambda}(x,t_0)$ ,  $x \in \overline{\Omega}$ , in view of Lemma 1 we have  $\tilde{u}(x,t) < \hat{u}_{\lambda}(x,t)$ , if  $(x,t) \in \overline{Q_0}$ ,  $\lambda > 0$ . Since  $\lim_{\lambda \to 0+} \hat{u}_{\lambda}(x,t) = \hat{u}(x,t)$ , then  $\tilde{u}(x,t) \leqslant \hat{u}(x,t)$ ,  $(x,t) \in \overline{Q_0}$ .  $\square$ 

LEMMA 3. Let  $a_0(t) > 0$ ,  $t \in [t_0, T]$ . Then an arbitrary function  $u \in C(\overline{Q_0}) \cap C^{2,1}(Q_0)$  such that Pu is the bounded in  $Q_0$  function, fulfil an estimate

$$|u(x,t)| \leqslant \max\{\max_{y \in \overline{\Omega}} |u(y,t_0)|, \sup_{(y,\tau) \in \Sigma_0} \frac{|Bu(y,\tau)|}{1 - G(y,\tau)}, \sup_{(y,\tau) \in Q_0} \frac{|Pu(y,\tau)|}{a_0(\tau)}\}, (x,t) \in \overline{Q_0}.$$
(5)

Proof. Let  $C \stackrel{\text{def}}{=} \max\{\max_{y \in \overline{\Omega}} |u(y, t_0)|, \sup_{(y, \tau) \in \Sigma_0} \frac{|Bu(y, \tau)|}{1 - G(y, \tau)}, \sup_{(y, \tau) \in Q_0} \frac{|Pu(y, \tau)|}{a_0(\tau)}\}$ . Consider a function  $\hat{u} \equiv C$ . It follows from conditions (A3)-(A5) and the choice of C that

$$P\hat{u}(x,t) \geqslant C(a(x,t) - F(x,t)) \geqslant C \cdot a_0(t) \geqslant Pu(x,t), \quad (x,t) \in Q_0.$$
 (6)

Using condition (A6), in view of definition of function  $\hat{u}$  we obtain

$$B\hat{u}(x,t) \geqslant C(1-G(x,t)) \geqslant Bu(x,t), \quad (x,t) \in \Sigma_0.$$
 (7)

It is obvious that  $\hat{u}(x,t_0) \geqslant u(x,t_0)$ ,  $x \in \overline{\Omega}$ . Hence and by (6),(7) and Lemma 2 we obtain  $\hat{u}(x,t) \geqslant u(x,t)$ ,  $(x,t) \in \overline{Q_0}$ . It can be shown analogously that  $u(x,t) \geqslant -\hat{u}(x,t)$ ,  $(x,t) \in \overline{Q_0}$ .  $\square$ 

LEMMA 4. Let  $a_0(t) > 0$ ,  $t \in [t_0, T]$ . Then arbitrary functions  $\{u_1, u_2\} \subset C(\overline{Q_0}) \cap C^{2,1}(Q_0)$  such that  $Pu_1$ ,  $Pu_2$  are bounded in  $Q_0$  functions, fulfil an inequality

$$\begin{aligned} |u_1(x,t) - u_2(x,t)| &\leqslant \max \big\{ \quad, \max_{y \in \Omega} |u_1(y,t_0) - u_2(y,t_0)|, \\ \max_{(y,\tau) \in \Sigma_0} \frac{|Bu_1(y,\tau) - Bu_2(y,\tau)|}{1 - G(y,\tau)}, \quad \max_{(y,\tau) \in Q_0} \frac{|Pu_1(y,\tau) - Pu_2(y,\tau)|}{a_0(\tau)} \big\}, \ (x,t) \in \overline{Q_0}. \end{aligned}$$

*Proof.* Let  $u_1, u_2$  be the same as in the formulation of lemma. Then

$$f(x,t,u_1(x,t);u_1(\cdot,t)) - f(x,t,u_2(x,t);u_2(\cdot,t)) = f(x,t,u_1(x,t);u_1(\phi t,t)) - f(x,t,u_2(x,t);u_1(\cdot,t)) + f(x,t,u_2(x,t);u_1(\cdot,t)) - f(x,t,u_2(x,t);u_2(\cdot,t)).$$

We have

$$f(x,t,u_1(x,t);u_1(\cdot,t))-f(x,t,u_2(x,t);u_1(\cdot,t))=f_*(x,t)u_{1,2}(x,t),$$

where  $f_*(x,t) = \frac{f(x,t,u_1(x,t);u_1(\cdot,t)) - f(x,t,u_2(x,t);u_1(\cdot,t))}{u_1(x,t) - u_2(x,t)}$ , if  $u_1(x,t) \neq u_2(x,t)$ , otherwise  $f_*(x,t) = 0$ ;  $u_{1,2}(x,t) \stackrel{\text{def}}{=} u_1(x,t) - u_2(x,t)$ ,  $(x,t) \in \overline{Q_0}$ .

By condition (A4) we obtain

$$f(x,t,u_2(x,t);u_1(\cdot,t))-f(x,t,u_2(x,t);u_2(\cdot,t))=f_{**}(x,t;u_{1,2}(\cdot,t)),$$

where  $f_{**}(x,t;\cdot):C(\overline{\Omega})\to\mathbb{R},\ (x,t)\in Q$ , is a family of linear continuous and nondecreasing functionals.

The preceding facts lead to

$$f(x,t,u_1(x,t);u_1(\cdot,t))-f(x,t,u_2(x,t);u_2(\cdot,t))=\tilde{f}(x,t,u_{1,2}(x,t);u_{1,2}(\cdot,t)),$$

where  $\tilde{f}(x,t,\xi;\cdot):C(\overline{\Omega})\to\mathbb{R},\ (x,t,\xi)\in Q\times\mathbb{R},\$ is a family of functionals with the same properties as the family  $f(x,t,\xi;\cdot):C(\overline{\Omega})\to\mathbb{R},\ (x,t,\xi)\in Q\times\mathbb{R}.$  Analogously

$$g(x,t,u_1(x,t);u_1(\cdot,t))-g(x,t,u_2(x,t);u_2(\cdot,t))=\tilde{g}(x,t,u_{1,2}(x,t);u_{1,2}(\cdot,t)),$$

where  $\tilde{g}(x,t,\xi;\cdot):C(\overline{\Omega})\to\mathbb{R},\ (x,t,\xi)\in\Sigma\times\mathbb{R}$ , is a family of functionals with the same properties as  $g(x,t,\xi;\cdot):C(\overline{\Omega})\to\mathbb{R},\ (x,t,\xi)\in\Sigma\times\mathbb{R}$ .

Denote  $\hat{f}_k(x,t) \stackrel{def}{=} Pu_k(x,t)$ ,  $(x,t) \in Q_0$ ,  $k \in \{1,2\}$ ;  $h_k(x,t) = Bu_k(x,t)$ ,  $(x,t) \in \Sigma_0$ ,  $k \in \{1,2\}$ . Subtracting from equation (1) for  $u_1$  the same equation for  $u_2$  we obtain

$$\tilde{P}u_{1,2}(x,t) \equiv \frac{\partial u_{1,2}(x,t)}{\partial t} - Lu_{1,2}(x,t) + a(x,t)u_{1,2}(x,t) - \\
-\tilde{f}(x,t,u_{1,2}(x,t);u_{1,2}(\cdot,t)) = \cdot,t))] = \hat{f}_{1,2}(x,t), \quad (x,t) \in Q_0, \tag{8}$$

where  $\hat{f}_{1,2}(x,t) \stackrel{\text{def}}{=} \hat{f}_1(x,t) - \hat{f}_2(x,t), \ (x,t) \in Q_0.$  Analogously

$$\tilde{B}u_{1,2}(x,t) \equiv u_{1,2}(x,t) - \tilde{g}(x,t,u_{1,2}(x,t);u_{1,2}(\cdot,t)) = h_{1,2}(x,t), \ (x,t) \in \Sigma_0, \quad (9)$$

$$u_{1,2}(x,t_0) = u^1(x,t_0) - u^2(x,t_0), \quad x \in \Omega,$$
(10)

where  $h_{1,2}(x,t) \stackrel{\text{def}}{=} h_1(x,t) - h_2(x,t), \quad (x,t) \in \Sigma_0$ . Using Lemma 3 and (8)-(10), we complete the proof .  $\square$ 

LEMMA 5. Let  $\nu \in V(a_0)$  and functions  $\{u_1,\,u_2\} \subset C^{2,1}_{loc}(Q) \cap C_{loc}(\overline{Q})$  are such that  $u_1-u_2 \in E_{\nu}(\overline{Q}),\, (Pu_1-Pu_2)/(a_0-\nu') \in E_{\nu}(Q),\, (Bu_1-Bu_2)/(1-G) \in E_{\nu}(\Sigma)$ . Then

$$|u_{1}(x,t) - u_{2}(x,t)| \leq \max \left\{ \sup_{(y,\tau) \in \Sigma} \frac{|Bu_{1}(y,\tau) - Bu_{2}(y,\tau)|e^{\nu(\tau)}}{1 - G(y,\tau)}, \right.$$

$$\sup_{(y,\tau) \in Q} \frac{|Pu_{1}(y,\tau) - Pu_{2}(y,\tau)|e^{\nu(\tau)}}{a_{0}(\tau) - \nu'(\tau)} \right\} e^{-\nu(t)}, \quad (x,t) \in \overline{Q}. \quad (11)$$

*Proof.* First we consider the case  $\nu=0\in V(a_0)$  and use the ideas of paper [7]. Denote  $\hat{f}_k(x,t)\stackrel{def}{=} Pu_k(x,t), \ (x,t)\in Q, \ k\in\{1,2\}; \ h_k(x,t)=Bu_k(x,t), \ (x,t)\in \Sigma, \ k\in\{1,2\}.$  Let  $\lambda(t)=\int\limits_T^t a_0(\tau)\,d\tau, \ \tau\in(-\infty,T]$ , and  $\gamma\in(0;1)$ . Let us multiply equation (1) and condition (2) for  $u_1$  and  $u_2$  by  $e^{\gamma\lambda(t)}$ . After simple transformations we obtain

$$P^{\gamma}\tilde{u}_{\gamma,k}(x,t) \equiv \frac{\partial \tilde{u}_{\gamma,k}(x,t)}{\partial t} - L\tilde{u}_{\gamma,k}(x,t) + (a(x,t) - \gamma a_0(t))\tilde{u}_{\gamma,k}(x,t) - f(x,t,\tilde{u}_{\gamma,k}(x,t)e^{-\gamma\lambda(t)};\tilde{u}_{\gamma,k}(\cdot,t)e^{-\gamma\lambda(t)})e^{\gamma\lambda(t)} = \hat{f}_k(x,t)e^{\gamma\lambda(t)}, (x,t) \in Q, \quad (12)$$

$$B^{\gamma}\tilde{u}_{\gamma,k}(x,t) \equiv \tilde{u}_{\gamma,k}(x,t) - g(x,t,\tilde{u}_{\gamma,k}(x,t)e^{-\gamma\lambda(t)}; \tilde{u}_{\gamma,k}(\cdot,t)e^{-\gamma\lambda(t)})e^{\gamma\lambda(t)} =$$

$$= h_{1,2}(x,t)e^{\gamma\lambda(t)}, \quad (x,t) \in \Sigma, \quad k \in \{1,2\}, \quad (13)$$

where  $\tilde{u}_{\gamma,k}(x,t) = u_k(x,t)e^{\gamma\lambda(t)}, \quad (x,t) \in Q, \quad k \in \{1,2\}.$ 

Let  $t_*$  be an arbitrary negative number,  $Q_* = \Omega \times (t_*, T], \Sigma_* = \partial \Omega \times (t_*, T]$ . It is easy to see that coefficients of the differential operators  $P^{\gamma}$  and  $P^{\gamma}$  fulfil the conditions

similar to conditions (A0)-(A7) for the coefficients of the operators P and B with  $a_0(1-\gamma)$  in place of  $a_0$ . Thus, in view of Lemma 4, by (12) and (13) we obtain

$$|\tilde{u}_{\gamma,1,2}(x,t)| \leq \max\{e^{\gamma\lambda(t_{*})} \cdot \max_{y \in \overline{\Omega}} |u_{1,2}(y,t_{*})|, e^{\gamma\lambda(T)} \cdot \sup_{(y,\tau) \in Sigma_{*}} \frac{|h_{1,2}(y,\tau)|}{1 - G(y,\tau)}, \\ \frac{e^{\gamma\lambda(T)}}{1 - \gamma} \cdot \sup_{(y,\tau) \in Q_{*}} \frac{|\hat{f}_{1,2}(y,\tau)|}{a_{0}(\tau)}\}, \quad (x,t) \in \overline{Q_{*}}, \quad (14)$$

where  $\tilde{u}_{\gamma,1,2} \stackrel{\text{def}}{=} \tilde{u}_{\gamma,1}(x,t) - \tilde{u}_{\gamma,2}(x,t), \ (x,t) \in \overline{Q}; \ \hat{f}_{1,2}(x,t) \stackrel{\text{def}}{=} \hat{f}_{1}(x,t) - \hat{f}_{2}(x,t), (x,t) \in Q; \quad h_{1,2}(x,t) \stackrel{\text{def}}{=} h_{1}(x,t) - h_{2}(x,t), \ (x,t) \in \Sigma.$ 

Since  $u_1 - u_2 \in E_0(\overline{Q})$  then  $|u_{1,2}(x,t)| \leq C_1$  for all  $(x,t) \in \overline{Q}$ , where  $C_1 \geq 0$  is a constant. Because  $e^{\gamma \lambda(t_*)} \to 0$  as  $t_* \to -\infty$  implies  $e^{\gamma \lambda(t_*)} \cdot \max_{y \in \overline{\Omega}} |u_{1,2}(y,t_*)| \to 0$  as  $t_* \to -\infty$ . Hence, letting first  $t_* \to -\infty$  in (14) and after letting  $\gamma \to 0+$  we obtain (11) for  $\nu = 0$ .

Let  $\nu \in V(a_0), \nu \neq 0$ . Let us multiply equation (1) and condition (2) for  $u_1$  and  $u_2$  by  $e^{\nu(t)}$ . After simple transformations we obtain (see (18),(19))

$$\begin{split} P_{\nu}\hat{u}_{k}(x,t) &= \hat{f}_{k}(x,t)e^{\nu(t)}, \quad (x,t) \in Q, \quad k \in \{1,2\}, \\ B_{\nu}\hat{u}_{k}(x,t) &= h_{k}(x,t)e^{\nu(t)}, \quad (x,t) \in \Sigma, \quad k \in \{1,2\}, \end{split}$$

where  $\hat{u}_k(x,t) = u_k(x,t)e^{\nu(t)}$ ,  $(x,t) \in \overline{Q}$ ,  $k \in \{1,2\}$ ;  $P_{\nu}v(x,t) \equiv \partial v(x,t)/\partial t - Lv(x,t) + (a(x,t)-\nu'(t))v(x,t) - f(x,t,v(x,t)e^{-\nu(t)}; v(\cdot,t)e^{-\nu(t)})e^{nu(t)}$ ,  $(x,t) \in Q$ ,  $B_{\nu}v(x,t) \equiv v(x,t) - g(x,t,v(x,t)e^{-\nu(t)}; v(\cdot,t)e^{-\nu(t)})e^{\nu(t)}$ ,  $(x,t) \in \Sigma$ ,  $v \in C^{2,1}_{loc}(Q)$ . It is easy to see that coefficients of the differential operators  $P_{\nu}$  and  $B_{\nu}$  fulfill the conditions analogous to conditions (A1)-(A6) for the coefficients of the operators P and  $P_{\nu}v(x,t) = v(x,t) - v(x,$ 

## 3. Proof of basic results

*Proof of Theorem 1.* To obtain an apriori estimate of the solution of Problem (1),(2) it suffices to set  $u_1 = u$ ,  $u_2 = 0$  and use Lemma 5.

Proof of Theorem 2 As a consequence of Lemma 5, we have the uniqueness of the solution.

Proof of Theorem 3. Consider first the case  $\nu = 0 \in V(a_0)$ . Let for all  $k \in \mathbb{N}$   $u_k$  be a solution of Problem  $(1_k) - (3_k)$ .

Based on Lemma 4 we have  $u_k(x,t)=0$  for all  $(x,t)\in\overline{\Omega}\times[-k,-k+1/2]$ . Let us extend the function  $u_k$  by zero on  $\overline{Q}\setminus\overline{Q^k}$  and denote these extensions again by  $u_k$   $(k\in\mathbb{N})$ . It is obvious that  $u_k\in C^{2+\alpha,1+\alpha/2}(\overline{Q})$  and  $u_k$  is a solution of Problem (1),(2) with  $f_k,\hat{f}_k,g_k$ ,  $h_k$  in place of  $f,\hat{f},g,h$ , respectively, we denote this by  $u_k=NZ_0^k(\hat{f}_k,h_k)$ ,  $k\in\{1,2,...\}$ . In view of Theorem 1 we have

$$|u_k(x,t)| \leqslant M_0, \quad (x,t) \in \overline{Q}, \quad k \in \mathbb{N}.$$
 (15)

We show that the restrictions of terms of sequence  $\{u_k\}$  on the closure  $\overline{Q'}$  of an arbitrary bounded subdomain Q' of domain Q is the fundamental sequence in  $C(\overline{Q'})$ .

Let for arbitrary  $\{k,l\} \subset \mathbb{N}$   $u_k = NZ_0^k(\hat{f}_k,h_k)$ ,  $u_l = NZ_0^k(\hat{f}_l,h_l)$ . Set  $\lambda(t) \stackrel{\text{def}}{=} \int_T^t a_0(\tau) d\tau$ ,  $t \in (-\infty,T]$ , and multiply the equalities  $(1_m)$  and  $(2_m)$ ,  $m \in \{k,l\}$ , by  $e^{\frac{1}{2}\lambda(t)}$ . After simple transformations we obtain

$$rac{\partial ilde{u}_m(x,t)}{\partial t} - L ilde{u}_m(x,t) + (a(x,t) - rac{1}{2}a_0(t)) ilde{u}_m(x,t) -$$

$$-f_m(x,t,\tilde{u}_m(x,t)e^{-\frac{1}{2}\lambda(t)};\tilde{u}_m(\cdot,t)e^{-\frac{1}{2}\lambda(t)})e^{\frac{1}{2}\lambda(t)} = \hat{f}_m(x,t)e^{\frac{1}{2}\lambda(t)}, (x,t) \in Q, \quad (16)$$

$$\tilde{u}_m(x,t)-g_m(x,t,\tilde{u}_m(x,t)e^{-\frac{1}{2}\lambda(t)};\tilde{u}_m(\cdot,t)e^{-\frac{1}{2}\lambda(t)})e^{\frac{1}{2}\lambda(t)}=$$

$$=h_m(x,t)e^{\frac{1}{2}\lambda(t)}, \quad (x,t)\in\Sigma,\tag{17}$$

where  $\tilde{u}_m(x,t) = u_m(x,t)e^{\frac{1}{2}\lambda(t)}, (x,t) \in \overline{Q}, m \in \{k,l\}.$ 

Let us show that for an arbitrary fixed natural number m the restrictions of terms of the sequence  $\{u_k\}$  on  $\overline{Q^m}$  compose fundamental sequence in  $C(\overline{Q^m})$ . We take an arbitrary value  $\varepsilon > 0$  and fix it. Let  $k_0 \in \mathbb{N}$  is such that  $k_0 > m$  and  $2M_0 \cdot e^{\frac{1}{2}\lambda(-k_0)} < \varepsilon$ . Let k and l be arbitrary natural numbers greater than  $k_0$  (constant  $M_0$  is from (3)). It leads to  $\hat{f}_k(x,t) - \hat{f}_l(x,t) = 0$ ,  $(x,t) \in Q^{k_0}$ , and  $h_k(x,t) - h_l(x,t) = 0$ ,  $(x,t) \in \Sigma^{k_0}$ .

Consider the restrictions of equalities (16) and (17) on  $Q^{k_0}$ . Based on Lemma 4 with  $\frac{1}{2}a_0(t)$  in place of  $a_0(t)$  we obtain

$$|\tilde{u}_k(x,t) - \tilde{u}_l(x,t)| \leqslant \max_{y \in \overline{\Omega}} |\tilde{u}_k(y,-k_0) - \tilde{u}_l(y,-k_0)|, \quad (x,t) \in \overline{Q^{k_0}}.$$
 (18)

By (15) we have  $\max_{y \in \overline{\Omega}} |\tilde{u}_k(y, -k_0) - \tilde{u}_l(y, -k_0)| \leq 2M_0 \cdot e^{\frac{1}{2}\lambda(-k_0)} < \varepsilon$ . This and (18) lead to  $\max_{(x,t) \in Q_{k_0}} |\tilde{u}_k(x,t) - \tilde{u}_l(x,t)| < \varepsilon$  for any  $k, l \geqslant k_0$ . Hence  $\max_{(x,t) \in \overline{Q^m}} |\tilde{u}_{k,l}(x,t)| < \varepsilon$ .

Therefore we have that the restrictions of the sequence  $\{\tilde{u}_k\}$  where  $\tilde{u}_k(x,t)=u_k(x,t)e^{\frac{1}{2}\lambda(t)},\ (x,t)\in\overline{Q}$ , on the set  $\overline{Q}^m$ , where m is an arbitrary fixed natural number, is fundamental sequence in  $C(\overline{Q}^m)$ . Thus, there exists function  $u\in C_{\mathrm{loc}}(\overline{Q})$  such that  $u_k\to u$  uniformly as  $k\to\infty$  on an arbitrary compact from Q. In view of (15) we have  $|u(x,t)|\leqslant M_0,\ (x,t)\in\overline{Q}$ .

Let us show that u is a solution of Problem (1),(2). Since for any  $k \in \mathbb{N}$   $u_k = NZ_0^k(\hat{f}_k, h_k)$ , we have

$$\frac{\partial u_k(x,t)}{\partial t} - Lu_k(x,t) + a(x,t)u_k(x,t) =$$

$$= f_k(x, t, u_k(x, t); u_k(\cdot, t)) + \hat{f}_k(x, t), \quad (x, t) \in Q.$$
 (19<sub>k</sub>)

Let  $\{\Omega_m\}_{m=1}^{\infty}$  be a sequence of domains  $\Omega_m \subset \Omega$ ,  $m \in \mathbb{N}$  such that  $\Omega_1 \subset \Omega_2 \subset ... \subset \Omega_m$  subset...,  $\bigcup_{m \in \mathbb{N}} \Omega_m = \Omega$ ,  $\operatorname{dist}(\Omega_m, \partial \Omega_{m+1} > 0)$ ,  $m \in \mathbb{N}$ ,  $\operatorname{(dist}(A, B)$  is a distance between the sets A and B). Set  $Q_{(m)} = \Omega_m \times (-m, T]$ ,  $m \in \mathbb{N}$ .

Let m be an arbitrary fixed natural number. By  $(19_k)$  and Theorem 10.1 of monograph [8; pp.238-239] we obtain  $||u_k||_{\alpha,\alpha/2}^{Q_{(m+1)}} \leq C_2$ ,  $k \in \mathbb{N}$ , where  $C_2 > 0$  is a constant which does not depend on k.

Using this,  $(19_k)$ , conditions of Theorem 3, in view of Theorem 10.1 of monograph [8; p.400] we obtain  $||u_k||_{2+\alpha,1+\alpha/2}^{Q_{(m)}} \leq C_3$ , where  $C_3 \geq 0$  is a constant which does not

depend on k.

Hence, and by well-known properties of space  $C^{2+\alpha,1+\alpha/2}(\overline{Q_{(m)}})$  it follows that for an arbitrary fixed number  $\gamma \in (0,\alpha)$  there exists a subsequence of sequence  $\{u_k\}_{k=1}^\infty$  which tends to u in  $C^{2+\gamma,1+\gamma/2}(\overline{Q_{(m)}})$ , the restrictions of u on  $\overline{Q_{(m)}}$  belong to the space  $C^{2+\alpha,1+\alpha/2}(\overline{Q_{(m)}})$ . Hence, using diagonal process, we conclude that there exists a subsequence  $\{u_k\}_{j=1}^\infty$  of sequence  $\{u_k\}_{k=1}^\infty$  such that for an arbitrary bounded domain  $Q' \subset Q$  located on the positive distance from  $\Sigma$  the restrictions  $u_{k_j}$  on  $\overline{Q'}$ ,  $j \in \mathbb{N}$ , compose a sequence which converges to the restriction of u on  $\overline{Q'}$  in  $C^{2+\gamma,1+\gamma/2}(\overline{Q'})$ , and  $u \in C^{2+\alpha,1+\alpha/2}_{loc}(Q)$ . Hence and by  $(1_k)$  we obtain that u is a solution of equation (1). The fulfilment of condition (2) follows from  $(2_k)$  and uniform convergence of  $\{u_k\}$  in  $\overline{Q^m}$  for an arbitrary fixed natural number m. Thus the proof of Theorem 3 is complete in the case of  $\nu = 0 \in V(a_0)$ .

Let  $\nu \in V(a_0)$ ,  $\nu \neq 0$ . Probem (1),(2) can be rewrited

$$\frac{\partial \hat{u}(x,t)}{\partial t} - L\hat{u}(x,t) + (a(x,t) - \nu'(t))\hat{u}(x,t) - -f(x,t,\hat{u}(x,t)e^{-\nu(t)};\hat{u}(\cdot,t)e^{-\nu(t)})e^{\nu(t)} = \hat{f}(x,t)e^{\nu(t)}, \quad (x,t) \in Q,$$
(20)

$$\hat{u}(x,t) - g(x,t,\hat{u}(x,t)e^{-\nu(t)};\hat{u}(\cdot,t)e^{-\nu(t)})e^{\nu(t)} = h(x,t)e^{\nu(t)}, \quad (x,t) \in \Sigma,$$
 (21)

where  $\hat{u}(x,t) = u(x,t)e^{\nu(t)}, \ (x,t) \in \overline{Q}$ .

Problem (20),(21) is similar to Problem (1),(2) with  $a_0 - \nu'$  in place of  $a_0$  in the case of  $\nu = 0 \in V(a_0)$ . This completes the proof of Theorem 3.  $\square$ 

*Proof of Corollary*. For the sake of simplicity without loss of generality we consider only the case of k=1, more precisely, we consider a problem

$$P_1 u_1(x,t) = \hat{f}_1(x,t), \qquad (x,t) \in Q^1,$$
 (22)

$$B_1 u_1(x,t) = h_1(x,t), \qquad (x,t) \in \Sigma^1,$$
 (23)

$$u_1(x,-1)=0, \qquad x\in\Omega. \tag{24}$$

Further we use the arguments similar to that in [4].

Without loss of generality we take  $a_0(t) > 0$ ,  $t \in [-1, T]$ . Let

$$v_0(x,t) = C, \qquad (x,t) \in \overline{Q^1},$$

where

$$C \stackrel{\mathrm{def}}{=} \max\{\sup_{(y,\tau) \in \Sigma^1} \frac{|h_1(y,\tau)|}{1 - G(y,\tau)}, \sup_{(y,\tau) \in Q^1} \frac{|\hat{f}_1(y,\tau)|}{a_0(\tau)}\}.$$

Define the sequence of functions  $\{v_p\}_{p=0}^{\infty}$  by the rule: if the function  $v_{p-1} \in C^{2+\alpha,1+\alpha/2}(\overline{Q^1})$  is known then a function  $v_p \in C^{2+\alpha,1+\alpha/2}(\overline{Q^1})$  is a solution of problem

$$\hat{P}v_p(x,t) \equiv rac{\partial v_p(x,t)}{\partial t} - Lv_p(x,t) + a(x,t)v_p(x,t) =$$

$$= f_1(x, t, v_{p-1}(x, t); v_{p-1}(\cdot, t)) + \hat{f}_1(x, t), \quad (x, t) \in Q^1,$$
(25)

$$v_p(x,t) = g_1^*(x,t,0;(\eta v_{p-1})(\cdot,t)) + h_1(x,t), \quad (x,t) \in \Sigma^1,$$
(26)

$$v_p(x, -1) = 0, \quad x \in \Omega, \tag{27}$$

where function  $\eta \in C_0^{\infty}(\Omega)$  is from condition (C1) of corollary,  $g_1^*(x,t,\xi;\cdot) = \xi(t+1)g^*(x,t,\xi;\cdot)$ ,  $(x,t,\xi) \in \overline{Q} \times \mathbb{R}$ .

It follows from Theorem 6.1 of monograph [8; p.513], that a sequence  $\{v_p\}$  is correctly defined, that is, for arbitrary  $p \in \mathbb{N}$  function  $v_p \in C^{2+\alpha,1+\alpha/2}(\overline{Q^1})$  is uniquely found.

Further, using our assumptions and the results of monograph [8] it can be shown that sequence  $\{v^p\}$  converges to the solution of Problem (22)-(24).

Proof of Theorem 4. Let  $\varepsilon > 0$  be an arbitrary number and  $(\hat{f}_1, h_1)$ ,  $(\hat{f}_2, h_2) \in \Pi_{\nu}$  such that  $\sup_{(y,\tau)\in Q} \frac{|\hat{f}_1(y,\tau)-\hat{f}_2(y,\tau)|e^{\nu\tau}}{a_0(\tau)-\nu'(\tau)} < \varepsilon/3$ ,  $\sup_{(y,\tau)\in \Sigma} \frac{|h_1(y,\tau)-h_2(y,\tau)|e^{\nu\tau}}{1-\hat{K}(y,\tau)} < \varepsilon/3$ , and  $u_i = NZ_{\nu}(\hat{f}_i, h_i)$ ,  $i \in \{1, 2\}$ . Hence, in view of Lemma 5 we complete the proof of Theorem 4.  $\square$ 

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